

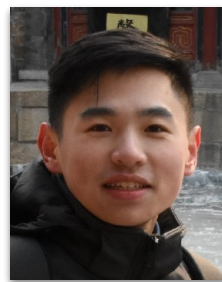
CRADLE: Cross-Backend Validation to Detect and Localize Bugs in Deep Learning Libraries



Hung Viet Pham¹



Thibaud Lutellier¹



Weizhen Qi²



Lin Tan³

¹University of Waterloo, Canada

²University of Science and Technology of China, China

³Purdue University, USA

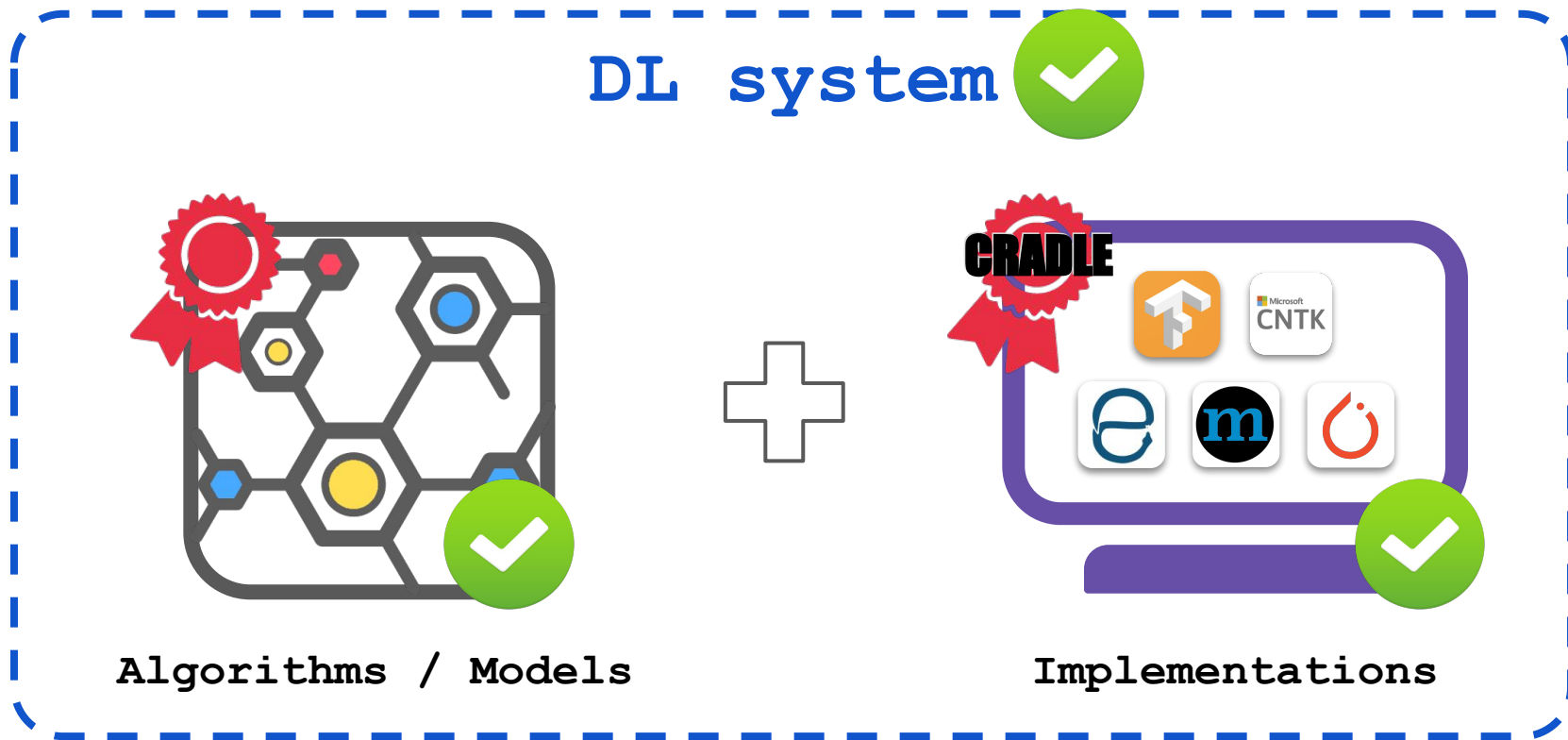


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Correct DL systems require correct implementations



DL libraries are hard to test and debug

- Intrinsic complexity
- DL system expected output is unknown
 - Correct programs should output expected output.
 - The ground truth is not the expected output because models are not perfect.

MobileNetV2

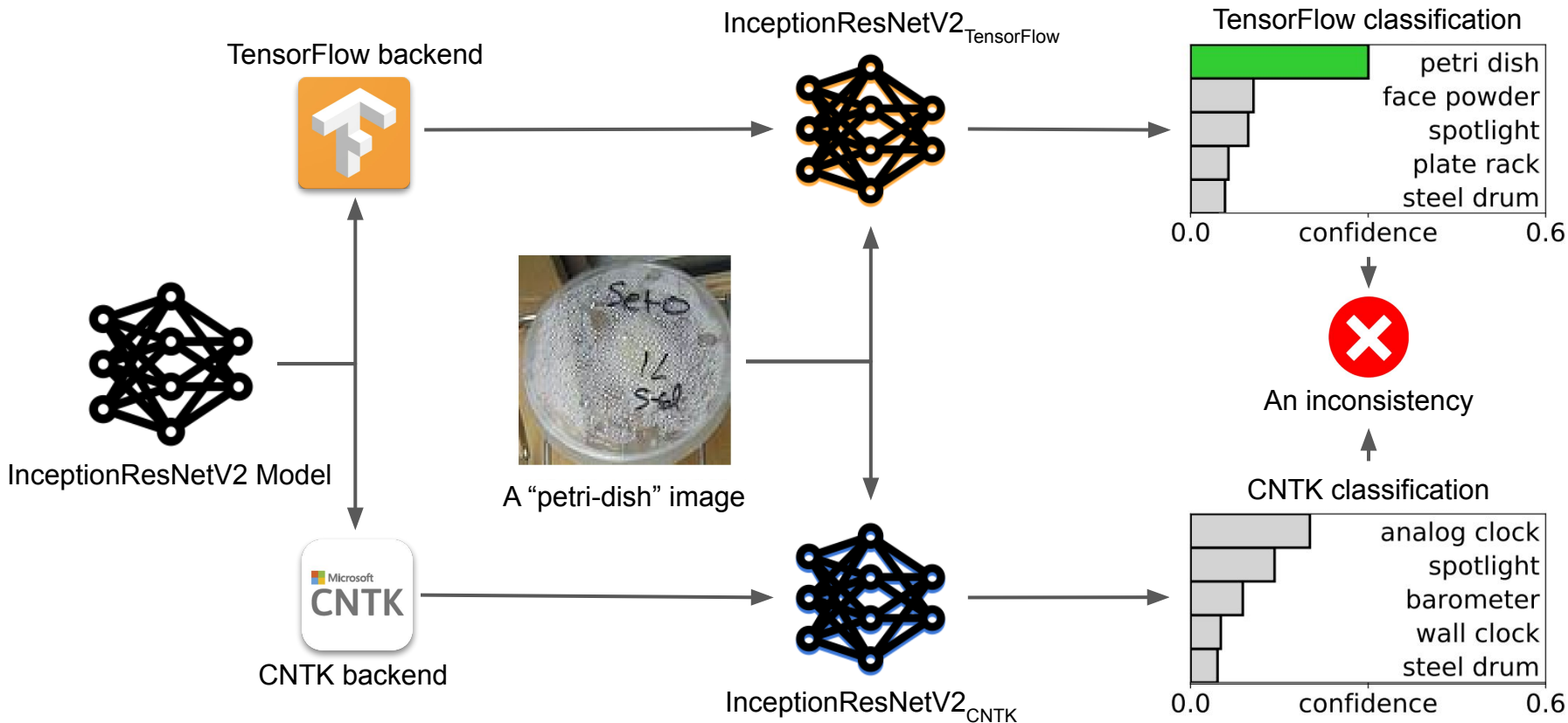
Expected output: tennis ball



MobileNetV2 - TensorFlow: banana

Ground-truth: banana

Idea: Differential testing



Batch_normalization bug

- The CNTK batch normalization formula was implemented incorrectly.
- The developers fixed the bug after we reported it.

```
- return (x-mean) / (C.sqrt(var)+epsilon)*gamma+beta  
+ return (x-mean) / C.sqrt(var +epsilon)*gamma+beta
```

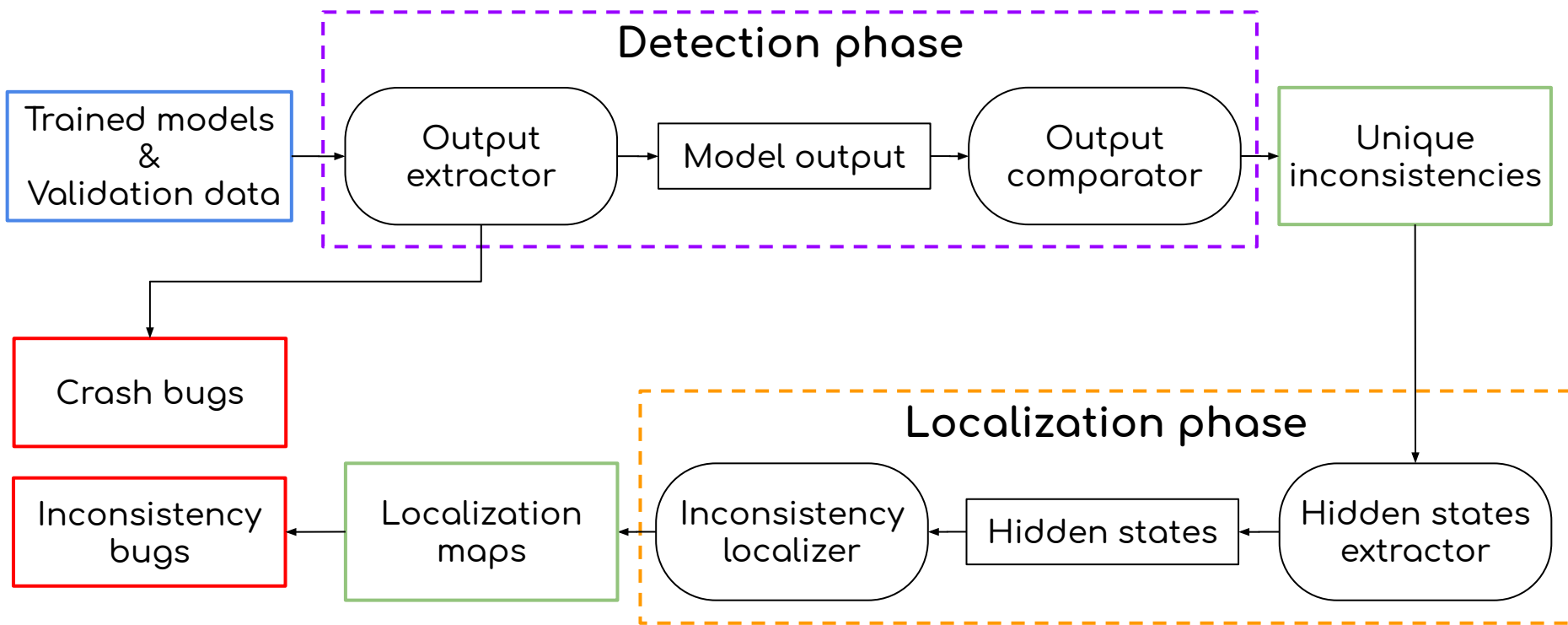
Differential testing: Challenges

- How to compare two implementations?
 - What metric to use?
 - What should be considered bugs?
- How to localize the faults?
 - How to find faults in the complex model executions?

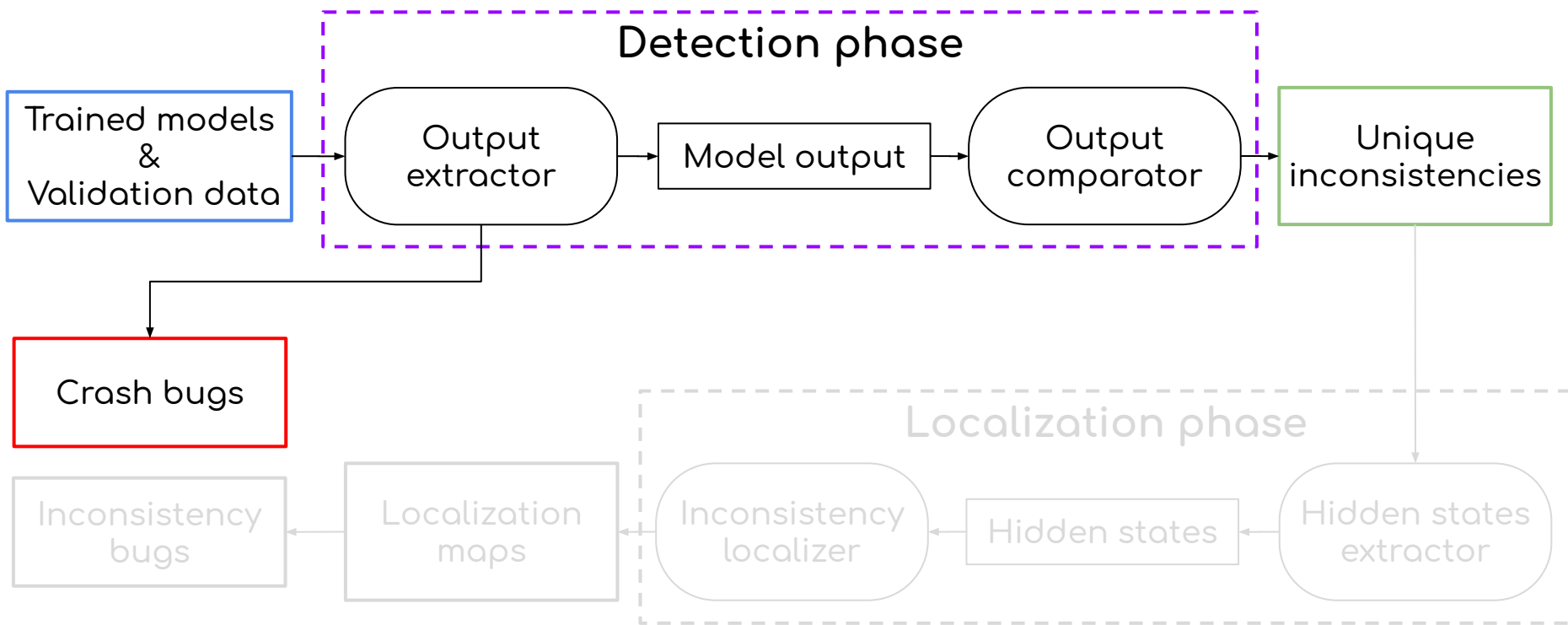
Differential testing: Ideas

- Two metrics measure the severity of the inconsistency for a set of input instances.
- Localization map compares intermediate states of DL models for fault localization.

CRADLE: Overview

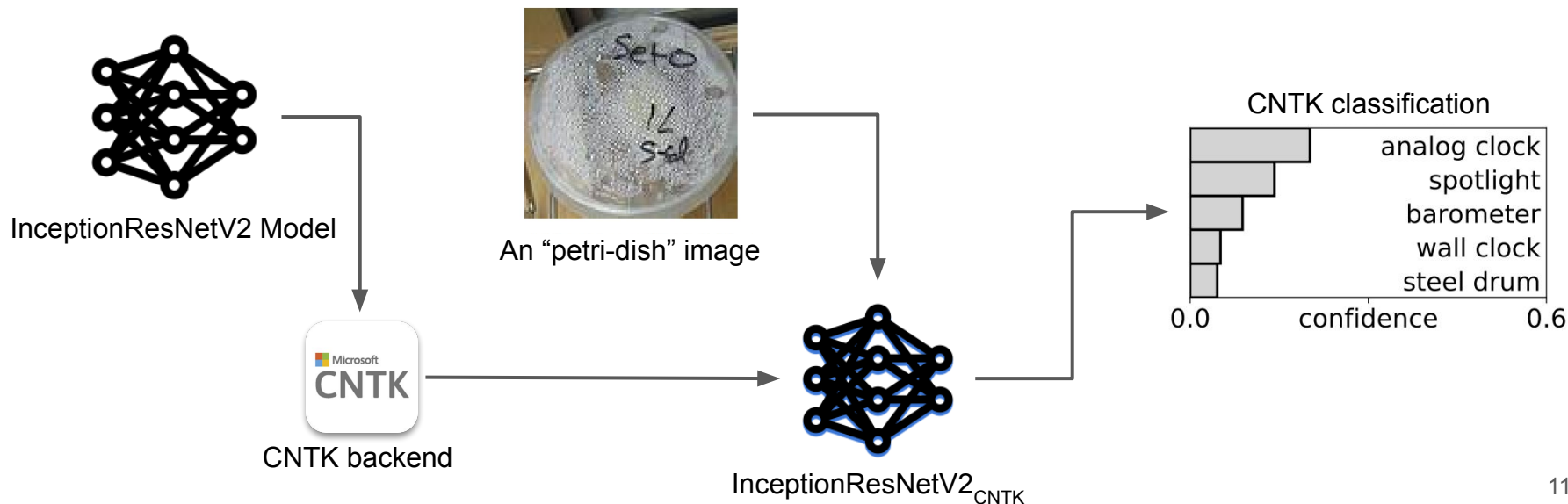


CRADLE: Detection phase



Output extractor

- Executes the models on different backends to obtain output
- Detects crashes



Output comparator: Distance metrics

Metrics calculate difference relatively to the ground-truth.

CLASS-based (Classification)

$$\sigma_{C,Y} = \begin{cases} 2^{k-\text{rank}_{C,Y}} & \text{if } \text{rank}_{C,Y} \leq k \\ 0 & \text{otherwise} \end{cases}$$

$$\text{D_CLASS}_{C,Y,Y'} = |\sigma_{C,Y} - \sigma_{C,Y'}|$$

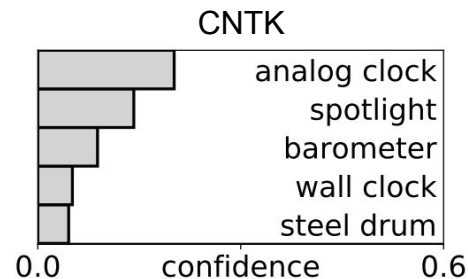
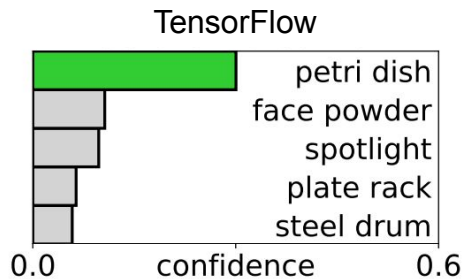
MAD-based (Regression)

$$\delta_{O,Y} = \frac{1}{N} \sum_{i=1}^N |Y_i - O_i|$$

$$\text{D_MAD}_{O,Y,Y'} = \frac{|\delta_{O,Y} - \delta_{O,Y'}|}{\delta_{O,Y} + \delta_{O,Y'}}$$

CLASS-based distance example

Top-5 classification



$$\sigma_{C,Y} = \begin{cases} 2^{k-\text{rank}_{C,Y}} & \text{if } \text{rank}_{C,Y} \leq k \\ 0 & \text{otherwise} \end{cases}$$

$$\text{Rank}_{\text{petri-dish,TF}} = 1$$

$$\sigma_{\text{petri-dish,TF}} = 2^{5-1} = 16$$

$$\text{Rank}_{\text{petri-dish,CN}} > 5$$

$$\sigma_{\text{petri-dish,CN}} = 0$$

$$\text{D_CLASS}_{C,Y,Y'} = |\sigma_{C,Y} - \sigma_{C,Y'}|$$

$$|\sigma_{\text{petri-dish,CN}} - \sigma_{\text{petri-dish,CN}}| = 16$$

Inconsistency triggering input (ITI)

- An input instance triggers a distance larger than a threshold (T_C and T_M)
 - E.g.,: “petri-dish” image is an ITI given $T_C = 8$.

Theano: Indian elephant

TensorFlow: groom

CNTK: groom



TensorFlow: banana

CNTK: tennis ball

Theano: tennis ball



CNTK: Arabian camel

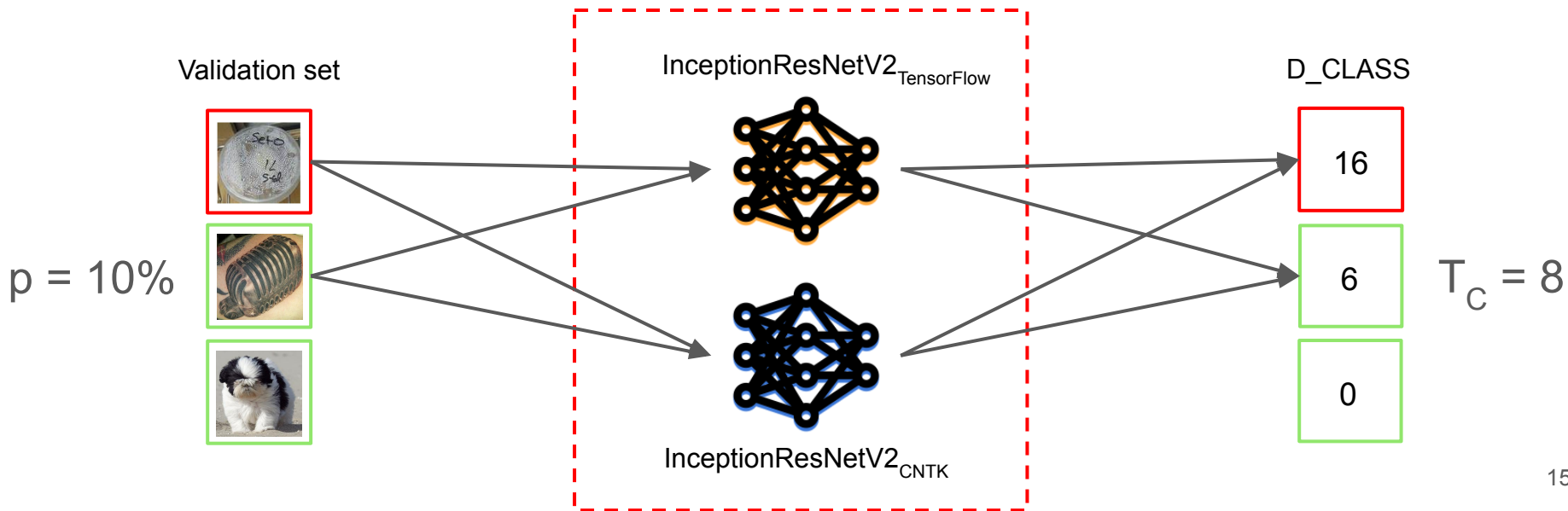
TensorFlow: hen

Theano: hen

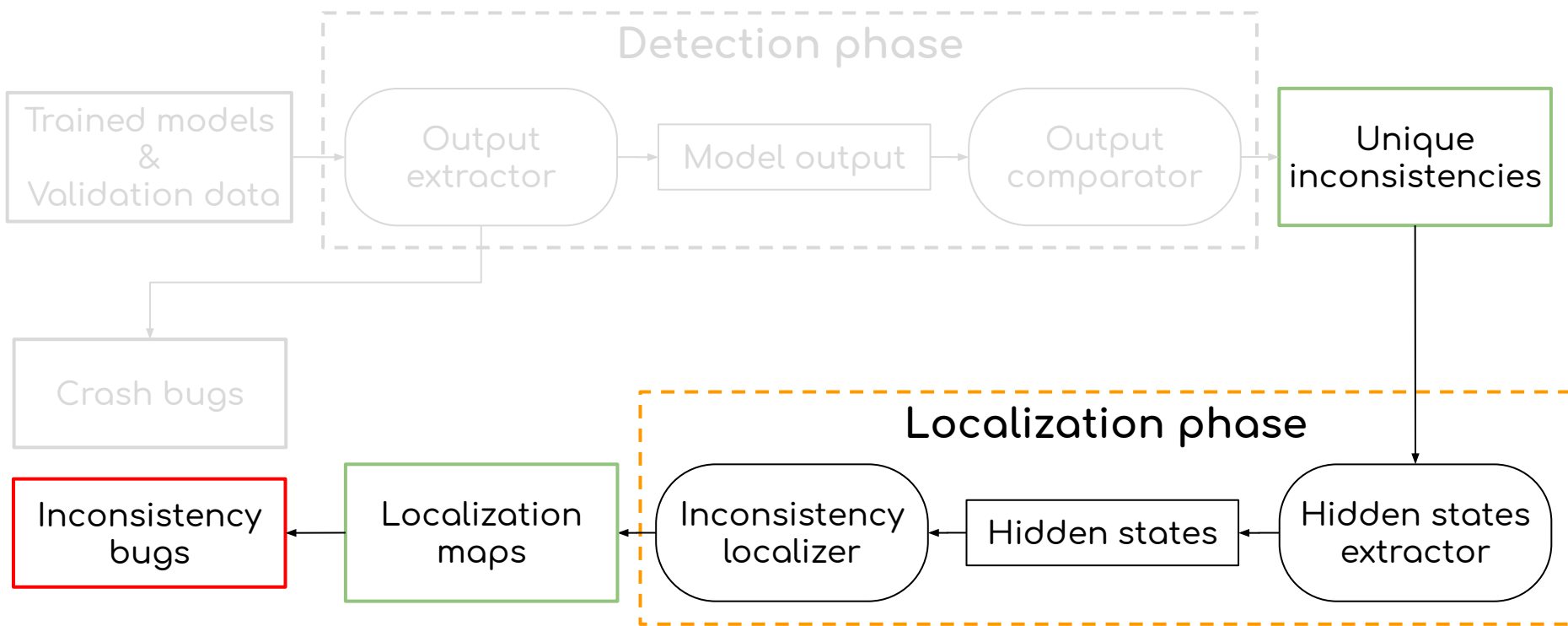


Detect inconsistency

- An inconsistency is a pair of implementations that triggers more than $p\%$ of ITIs over the validation set

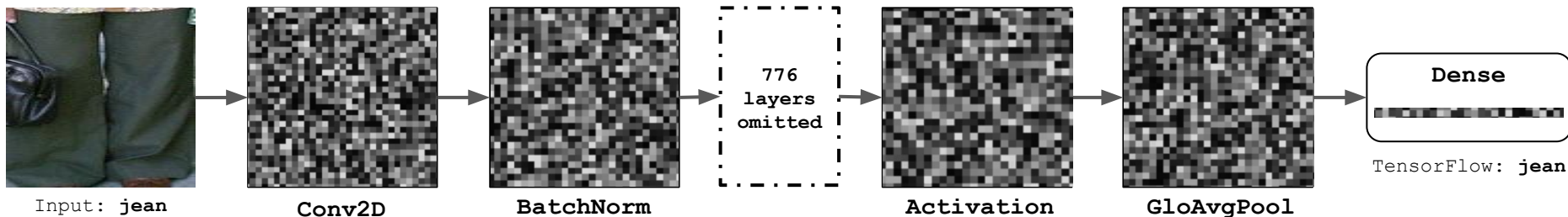


CRADLE: Localization phase



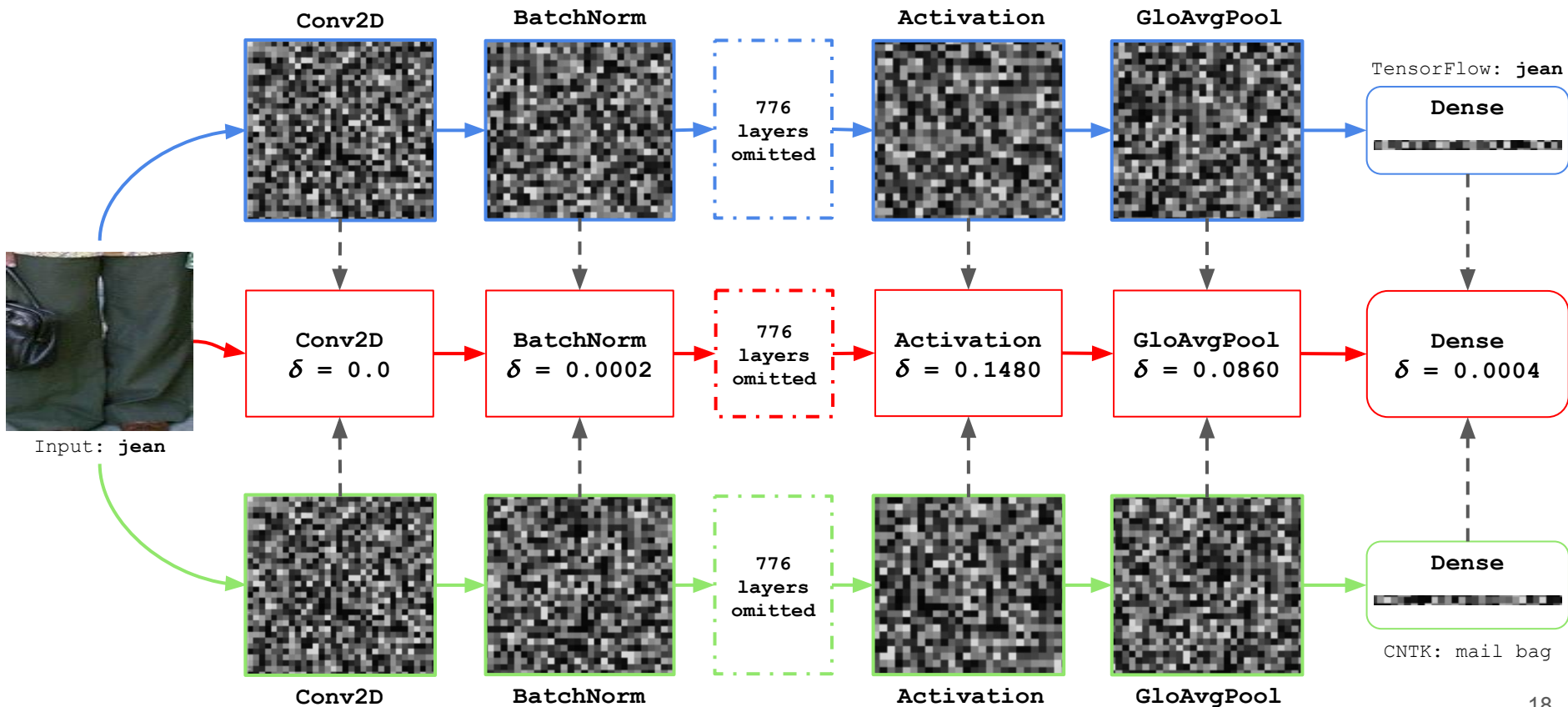
Hidden state extractor

- The “most inconsistent” input per inconsistency is used.
- The network structure + hidden states are considered as the network execution graph.
- Hidden states are output of hidden layers.



InceptionResNetV2 execution graph on TensorFlow

MAD differences

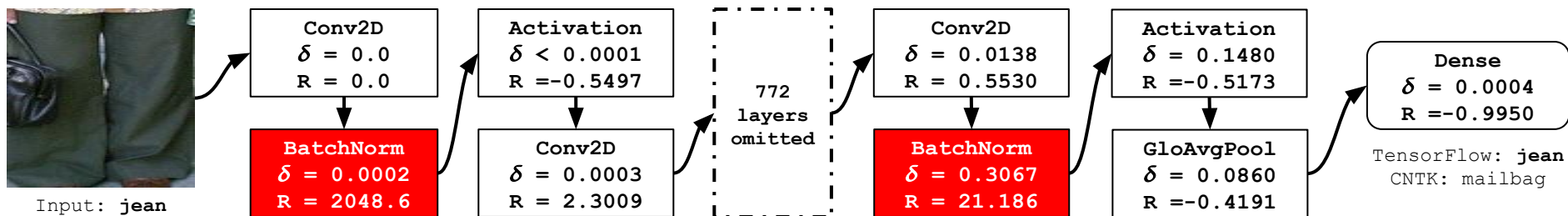


Inconsistency introduction rate

- Calculate the rate of change
 - ϵ prevent division by zero
- Highlight executions with R above the third quantile

$$R_L = \frac{\delta_{S_L, S'_L} - \delta_{pre}}{\delta_{pre} + \epsilon}$$

$$\delta_{pre} = \max_{l \in pre(L)} (\delta_{S_l, S'_l})$$



InceptionResNetV2 localization map between TensorFlow and CNTK

Result

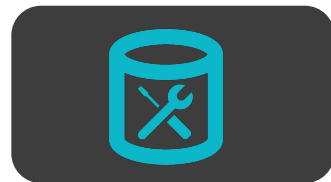
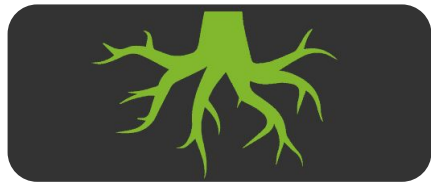
104 unique inconsistencies

3 backends

28 models **11** datasets

7 inconsistency bugs **5** crash bugs

7 inconsistency bugs



Batch normalization

BatchNormalization

Padding scheme

Conv2D variant

Pooling scheme

AveragePooling2D

Parameter organization

Trainable Conv



Localization is helpful

Relevant to the causes of all **104** unique inconsistencies

First



One of



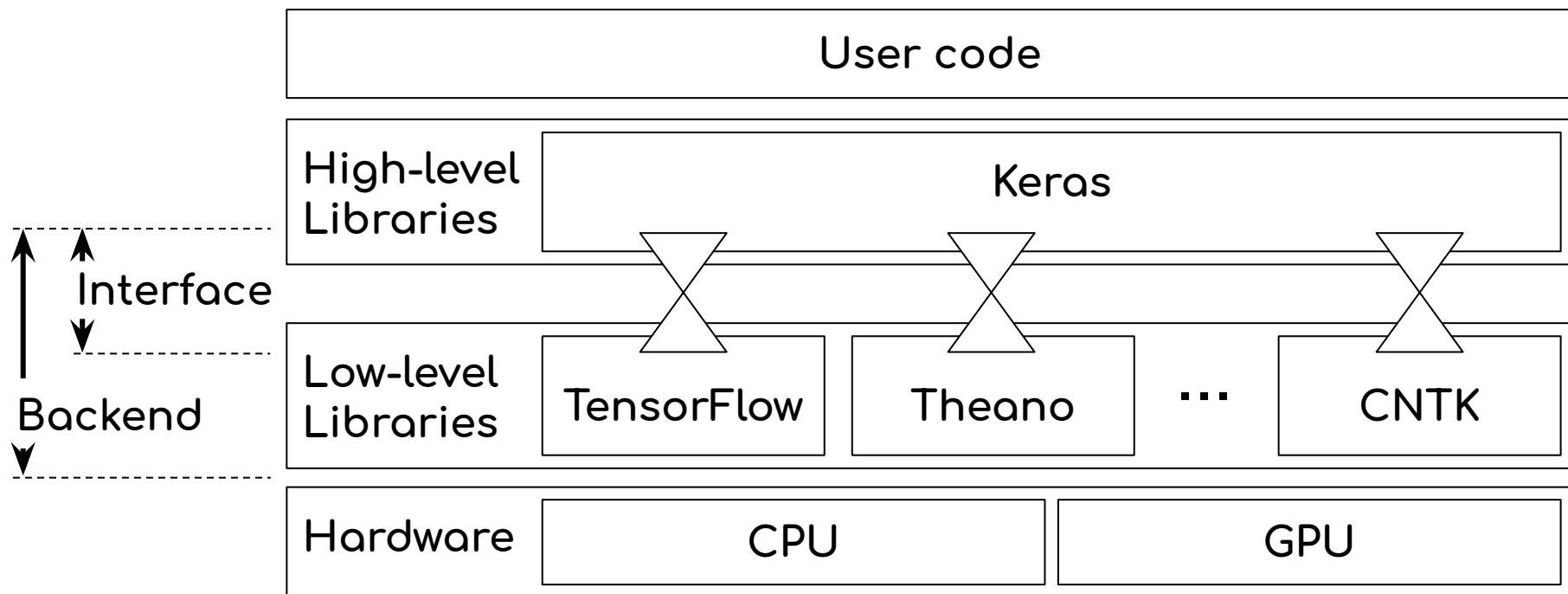
Relevant



Conclusion

- CRADLE applies differential testing on DL implementations and localize faulty functions by tracking error propagation.
 - Detects 7 confirmed inconsistency bugs and 5 crash bugs
 - Helps find root causes of all 104 unique inconsistencies using localization maps
- Inconsistencies are common and widespread.
- We call for more attention to testing of DL libraries.

DL system overview



Group unique inconsistency

- A group of inconsistencies with the same inconsistency pattern between the same pair of implementations
 - Inconsistency pattern is the distribution of metric distance

Id	Keras	Backends	Model	Inconsistency pattern					
				16	15-8	7-4	3-2	1	0
1	2.2.2	TF-CN	Xception	10	202	147	100	85	4456
2	2.2.2	TF-CN	NASNetLarge	5	132	86	77	65	4635
3	2.2.1	TF-CN	Xception	10	202	147	100	85	4456
4	2.2.1	TF-CN	NASNetLarge	5	132	86	77	65	4635

Suggested settings

- Grid search on T_C , T_M , and p values
- Optimal settings (most inconsistency without false negative and false positive) are:
 - CLASS-based: $T_C = 8$ and $p = 0\%$
 - MAD-based: $T_M = 0.2$ and $p = 0\%$
- Confirm using cross-validation

Dataset and hardware

- Dataset:
 - 11 datasets including ImageNet, MNIST, Udachi Driving Challenge 2, etc.
 - 30 pre-trained models
- Hardware:
 - Xeon E5-2695
 - NVIDIA Titan Xp

Detected inconsistencies

Dataset	Instances	# of Inconsistencies		
		TH-TF	TF-CN	CN-TH
ImageNet	5,000	10 (34)	21 (54)	18 (46)
Driving	5,614		3 (9)	3 (12)
MNIST	10,000		3 (9)	3 (12)
Thai MNIST	1,665		1 (3)	1 (4)
KGS Go game	12,288	2 (14)	3 (12)	3 (15)
Anime Faces	14,490	1 (5)		1 (6)
Dogs VS Cats	832		2 (6)	2 (8)
Dog species	835		3 (8)	3 (9)
Faces	466	2 (14)	3 (8)	6 (15)
Pokedex	1,300	1 (14)	1 (3)	2 (15)
GTSRB sign	12,630	2 (14)	2 (5)	2 (7)
		18 (95)	42 (117)	44 (149)
Total		104 (361)		

The numbers outside and (inside) brackets are the unique and (total) number of inconsistencies respectively.

Comparison to accuracy

- Detect inconsistency if the top-k accuracy difference is above a threshold T_{AC}
- We pick k between 1 to 5 and T_{AC} between 0 and 50
- With $T_{AC} = 0$, top-1 accuracy detects the most inconsistencies (305) but still missed 35
 - E.g., for the *Dog species* model, the `Batch_normalization` bugs induce inconsistency between TensorFlow and CNTK
 - However, those backends got identical top-1 (29.9%) and top-5 (64.4%) accuracies

Future work

- Detect inconsistencies and bugs in training code
 - Harder since training is non-deterministic
- Generate mutated models using fuzzing to expand testing set
- Testing with only one backend with equivalent models